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Impacts of EVChargingon Distribution Grid with Solutions

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Abstract— Due to the rise in fuel prices, the depletion offossilresources, and environmental concerns, electrical vehicles are a technology that shows the most promise and offeranal ternative to internal combustion engines. The analysis of the effects of grid charging for electric vehicles and its method of mitigation is the primary focus of this paper. The effects

ofelectricalvehiclegridchargingarecompleteintheMATLABS imulinkenvironment.Inordertostabilizethegridagainstthepene trationofelectricvehicles,ahybrid control approach is created, with the outer controllerbeingafuzzycontrollerandtheinnercontrollersbeingvectorcontroltechnique-

basedproportionalintegralcontrollers.Results for charging vehicle batteries using hybrid and PIcontroltechniquesarecompared,demonstratingtheusefulnes s of the suggested model and the capacity of thecontrolsystemforquickdccharging.Atlast,thesolutionstoE VPenetration ingrid forupcomingyearsare given.

Index Terms—hybrid control, Drivers for EV Penetration, Solutions to EV Penetration, Charging Methodologies.

nitrogen

Hydrocarbons,

1. Introduction

dioxide,

lead,

monoxide, sulphurdioxide, and particulate matterare the main po llutantsthatvehicleemits. India's hasamassive automobile indust ry,thefourthlargestintheworld,accountsforasignificantportion ofvehicular pollution. The population of electric vehicles is growi nginIndiaatapaceof37.5%, accordingto[1]. Additionally, the government isgiving electric vehicles [2] and charging moreattention. According to reference [4], the positioning of char gingstationshasbeensuggestedtomaximizetheireffectiveness and supply the necessary amount of power. Electric vehicles are also gaining worldwide attention andacceptance as a promising potential long-term solution forsustainable mobility [5]. In order demandresponseservicesbyelectrifyingthegridorloweringcha rgingrates, it describes a system in which pluginelectricvehicles, such as vehicle-togrid(V2G), electric cars(BEVS), and pluginhybrids(PHEVs),connectwiththepower grid. Four broad categories can be used categorizetheactivepowermarketsforV2G.Baseload,shaving, spinning reserves, and regulation are these four categories[6]. V2G is rarely utilized for base load power because itconsumes a lot of battery charge. Peak shaving takes placewhen the demand for predictable power is at its maximum. To comply with contract requirements, thread reserves must be incorporated into the system power design. The yaretypic

ally called 20 times annually on average. To maintain aconsistent voltage and frequency, active regulation is

used. When the carbattery is charged from the mains, it operates in

Page No: 1

G2Vmode.GridstabilitywillbeseriouslyimpactedbyongridvehiclechargingasEVpenetrationrisesasaresultofunco ordinated grid-to-vehicle (G2V) charging. Power qualityissues,transformerlosses,linelosses,lineheatingissu es,andhigher reactive power consumption can all be brought on bythese charging effects. These problems may result in generalpowersystemandvoltagestabilityproblems,aswell assystemnetworkcrashes[7],[8].Theresearchersconstruct edamodel in which the EV effect on the load curve could beanalyzed to determine peak load periods for charging

andpeakloadtimesfordischargingthecar, ortheyworkedont hebest placement of automobiles in the distribution networkusingthegeneticalgorithmasa Smartcontrol. Charg e-related disadvantages are lessened. [9], [10], [11]. Agroupofcontroltechniquesknown as intelligent controlma kesuse of artificial intelligence (AI) computing techniques su chneural networks, Bayesian probability, fuzzylogic, and machine learning. Genetical gorithms and evolutionary

computation [12]. The integration of vehicles with the grid is the main concern of this article. The electric vehicle charging station design that has been suggested is appropriate for quick decharging of electric automobiles.

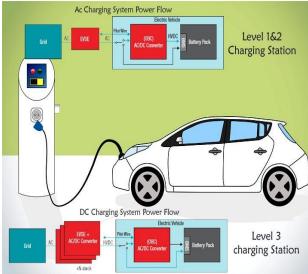


Fig. 1 EV charging Methodologies [13]

For EV charging, various technologies are available. Wiredsystems employing conductive technologies are by

themostwidelyusedbecausetheycaneasilyensuretherequis itepower level, safety, and interoperability with the majority ofcars.5; nonwired methods (based on inductivity

principles)arebeinginvestigatedforhighwayapplications. Batteryswapisintendedforhigh-

speedapplications(carracing),butit may also be ideal for fleets, sharing, and/or heavy-dutyapplications.AlternatingCurrent(AC)infrastructuresr elyoncar on-board chargers and are power limited due to vehiclesizeandexpense.Off-

boardpowerelectronicsinstalledatthecharging stationareusedinDCinfrastructures. This enables

larger / bulkier / more expensive components, resulting incharging power of up to 350 kW in today's best performingdevices. Although the trend in the early years of E-mobilitywas to increase AC charging power (up to 43 kW in somemodels), the current approach is to limit AC charging to lessthan22kW(typically7kWsinglephaseor11kWthree-

lessthan22kW(typically/kWsinglephaseor11kWthree-phase). Fast charging will, in reality, be achieved by aDC charger, which is becoming standard equipment for allEVs[14].

2. SystemConfiguration

To observe the impacts of electric vehicle penetration onseveralelectricalparameters, such as DC bus voltage, current, active power, reactive power, harmonics, powerfactor, simulations of the impact of this penetration are runi nthe MATLA Benvironment. In order to deliver continuous debus voltage with unity power factor in rapid charging modefor electric vehicles, hybrid control technology offers quickadjustments. The control architecture for decoupling usesalignment with PI regulators to a dq synchronous referenceframeorientation. In the voltages our cecon verter, as yn chronouslyrotatingdqreferenceframeisemployed.Gridsynchr onizationisacrucialandessentialcomponentofupstream converter control, and PLL (Phase locked loop) isemployed purpose [15]. Internal and external controlloopsarethefoundationofthehybridcontroltechniqueus edhere[16]. While the outer loop regulates the dcvoltage of the loa d, the inner loop controls the power flowing between thedc connection and the grid. Utilizing the vector technique, proportional integral controllers are employed as inter nalcontrollers and the fuzzy controller is built as an externalcontroller. The PI control approach is used with

logiccontrol. Giventhatitdoesn'trequireaccurate.noiselessinpu ts, fuzzy logic is naturally robust. Fuzzy logic can beadjusted. Any system can be easily managed and expanded upon without the need to start from scratch. Since FLCexecutes the user-defined rules that control the system, it issimpletoaddto,enhance,oraltersystemfunctionality.Here,the internal vector control technique is combined with an external fuzzy control technique and PI controllers to provide qnick dynamicresponse, lower harmonic generation, and enhance power factor while maintaining a constant de busvoltage. For quick de charging of electric vehicle batteries, the notion presented here might be quite helpful. There areseveralpartsthat describethestudiesthatwere done.

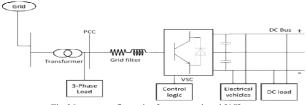


Fig. 2 System configuration for proposed work [17]

The system configuration for examining the effects of carcharging is shown in Figure 2. A transformer and grid filterare used to link a 30 MVA generator to a 3-phase, 3-levelvoltage source converter. The reduction of harmonics is afilter'sfunction.Bycarefullychoosingadccapacitor,ripplesand harmonics on the dc side of the voltage source convertercan be effectively managed. Transformers are used to linkvoltagesourceconverterstotheacsystem,asseeninFigure 1.Thetransformer'sjobistoconvertacvoltagetothenecessarylev elofacvoltageforcarDCcharging.Bymanagingthecurrentsthat

tiveandreactivepower.

Reactors lower the high frequency harmonic contents of theac currents that are brought on by the switching operation

oftheIGBTsbyactingasfiltersaswell. There are two capacito rs of the same size on the DC side. The needed dcvoltagedeterminesthesizeofthesecapacitors. Thedccapa citor's main purpose is to offer a low inductive path forthe turn-off current. It also functions as an energy storagedevice to regulate the power flow. Additionally, a capacitorlowers dc side voltage ripple. The energy storage device forvoltage source converters on the ac inductor sincetheyfunctionascontinuouscurrentsources. The voltagesourceconverterfunctionsasaconstantvoltagesour ceontheDCside, and it needs a capacitor as an energy storaged evice. In order to evaluate the effects of battery charging, loads areapplied to both the ac and dc sides, as is standard procedure. Table 1 displays the model definition forthesystem setup.

TABLE1MODELSPECIFICATIONS [17]

TABLETWIODELSFECIFICATIONS [17]					
Descriptions	Value				
Voltage source converterrating	500VoltsDC,500kW				
ACSupply:three-phase	500V,30MVA,50Hz system				
Load	Ac side 1MW&500KVAR, DC side 400kwincludingelectricvehiclebatteries				
DcLink:2capacitors	25000mF				
SwitchingFrequency	1620Hz				

The MATLAB Simulink battery model is used for analysis. 3. Control Strategy

ManyVSCcontrolapproaches,includingvoltagemodecont rol, current mode control, and vector control technique,havebeencreatedbytheresearcherswithvarioust echniques,algorithms and battery modelling [18]-[20]. It is possible touserandommodulation,fixedfrequencymodulation,orbo th.Linear (or Ramp Comparison) Control, Hysteresis Control,and Predictive Control are the three main categories that canbetakenintoconsiderationwhilediscussingthefundame ntalcontrol methods. However, new and novel approaches

tocurrentregulationhavebeenintroduced,includingfuzzyl

ogic controls, neural networks, and delta and sigma deltamodulation[21],[22].Numerous variations enhancementsof the fundamental ideas have been produced for each ofthese categories as a result of the research vast theseconverters. Voltagesource converters are used in every application nowadays because they have fast response times, high accuracy levels, and high performance requireme nts. Asthese attributes become more and more important, there is agrowing demand for low-cost, dependable, and high-qualitymethods. There is a need to compare and summaries thequalities of the available solutions because there many different ways [21]. The rear eals os ever a lauthoritativebooks detailing the state of the art for PWM approachesgenerally [21] and for VSI current regulation [22]. The mostwidely utilized type of control for VSC is vector control. Byestablishing a control approach based on the energy stored intheDC-linkcapacitor,DClinkvoltagemanagementisaccomplished. The control uses PΙ regulators

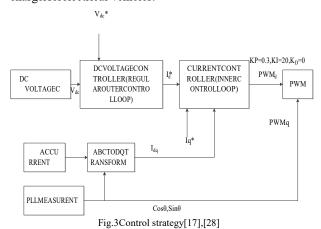
erto decouple. Active and reactive power can be independentlycontrolled using a synchronously rotating dq reference

frameinvoltagesourceconverters. Gridsynchronizationisaness ential component of grid side converter control. A PLL(phaselockedloop) is employed for this reason

Theinnerandoutercontrolloopsarethefoundation of the vector controllechnique used here. While the outer loop regulates the load's DC voltage, the inner loop controls power between the DC link and the grid. With constant DC

busvoltage, vector control technology provides quick

dynamicresponse, lowersharmonics, and boostspower factor. The concept presented here will be very helpful forquickly DC charging the batteries of electric vehicles. InFigure 3, a control technique is displayed. 4depictseveryelementrequiredforthevectorcontroltechnique. The grid-connected AC/DC converter for batterycharging is configured as shown in Figure 4. Analysis of theeffects of vehicle battery charging on the grid will be greatly aided by a understanding of the control thorough function ofthevoltagesourceconverter. Understandingthis will facilitate creation of an appropriate fast slow chargerforelectrical vehicles.



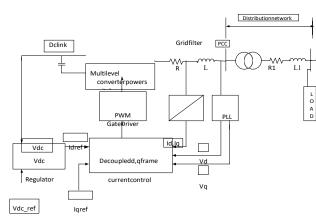


Fig.4ConfigurationofgridconnectedAC/DCConverterforbattery charging

The suggested control strategy makes use of active and reactive power calculations, direct-quadrature-

zerotransformationequations, and aphase-

lockedloop(PLL)algorithm to synchronize with the utility grid voltage.

Thephasecurrentsia,ib,andic,aswellastheutilityvoltagesvsa,vs b, and vsc, are transformed from a-b-c coordinates to a d-qframe using the Park transformation and t generated by the PLL. The following equations can be used to characterize the d-

components:
$$\begin{bmatrix} v \end{bmatrix} = \begin{vmatrix} \sin(wt) & \sin(wt - \frac{2\Pi}{3}) & \sin(wt + \frac{2\Pi}{3}) \end{bmatrix} \begin{bmatrix} v_{sa} \\ v_{q} \end{bmatrix} = \begin{vmatrix} \frac{1}{\sqrt{3}} \\ \cos(wt) & \cos(wt - \frac{3}{3}) & \cos(wt + \frac{3}{3}) \end{vmatrix} s \begin{vmatrix} v_{sb} \\ v_{sb} \end{vmatrix} = \begin{vmatrix} v_{sb} \\ v_{sb} \end{vmatrix}$$

$$\begin{bmatrix} i \end{bmatrix} & \begin{bmatrix} \sin(wt) & \sin(wt-\frac{2\Pi}{3}) & \sin(wt+\frac{2\Pi}{3}) & \sin(wt+\frac{2\Pi}{3}) \end{bmatrix} i \\ \begin{vmatrix} i \\ i \\ q \end{vmatrix} \end{bmatrix} & \begin{bmatrix} \sin(wt) & \sin(wt-\frac{2\Pi}{3}) & \sin(wt+\frac{2\Pi}{3}) \end{bmatrix} i \\ \begin{vmatrix} \cos(wt) & \cos(wt-\frac{2\Pi}{3}) & \cos(wt+\frac{2\Pi}{3}) \end{bmatrix} i \\ \begin{vmatrix} \sin(wt) & \sin(wt-\frac{2\Pi}{3}) & \sin(wt+\frac{2\Pi}{3}) \end{bmatrix} i \\ \begin{vmatrix} \sin(wt) & \sin(wt-\frac{2\Pi}{3}) & \sin(wt+\frac{2\Pi}{3}) & \sin(wt+\frac{2\Pi}{3}) \end{bmatrix} i \\ \begin{vmatrix} \sin(wt) & \sin(wt-\frac{2\Pi}{3}) & \cos(wt+\frac{2\Pi}{3}) & \sin(wt+\frac{2\Pi}{3}) &$$

Following the aforementioned transformation, the three-phase instantaneous active power and reactive power in the d-qframe are determined using the three-

phasegridvoltagesandcurrentsasgiveninthefollowingtwoequa tions.

$$\frac{3}{p} = (\underbrace{(v \times i)}_{1} + (v \times i)) \qquad q \qquad q$$

$$\frac{3}{q} = (\underbrace{(v \times i)}_{2} + (v \times i)_{1} + (v \times i)_{1})_{1}$$

Thecomputed instantaneous active and reactive power sinclude oscillation and average components. The outer PI control lloop is applied to track the difference between reference and actual DC bus voltage. PI controller generates active current reference i*d and reactive current reference i*d, as shown in the following equations:

 $Where k_{pp} and k_{pq} are proportional constants, and k_{ip} and k_{iq} are integral constants for the used PI controllers. P_{ref} is the reference of the charging power, and Q_{ref} is the reference value of the reactive power required by the AC grid. The control of the converter is designed by integrating inner loop current and outer voltage loop (DC bus voltage). Comparing the voltage reference with the actual voltage in the outer loop results in the current reference, this is used for the inner$

loopcontrol.Hence,theinnerPIloopsareestablishedbycompari ngactualmeasuredlinecurrentsobtainedbyutilizingtheparktran sformationmatrixwiththecurrent

reference (obtained using Equations (5) and (6)). The results(e_d and e_q) are first added with the decoupling terms and arethen normalized by the DC-link voltage (the battery voltage)to get the duty ratios in the d–q coordinate. These calculations are summarized as follows:

calculations are summarized as follows:
$$\begin{bmatrix} d_{d} \\ d_{q} \end{bmatrix} = V_{dc} = \begin{bmatrix} e_{d} + v_{d} + 3wl \times i_{q} \\ e_{q} + v_{q} - 3wl \times e_{d} \end{bmatrix} \qquad 7$$

$$\begin{bmatrix} D_{a} \\ D_{d} \end{bmatrix} = V_{dc} = \begin{bmatrix} e_{q} + v_{q} - 3wl \times e_{d} \\ e_{q} + v_{q} - 3wl \times e_{d} \end{bmatrix} \qquad 8$$

$$\begin{bmatrix} D_{a} \\ D_{d} \end{bmatrix} = V_{dc} = \begin{bmatrix} \sin(wt) & \cos(wt) \\ \cos(wt) \end{bmatrix} = \begin{bmatrix} D_{d} \\ \cos(wt) \end{bmatrix} = \begin{bmatrix} D_{d}$$

Toobtainthedutyratiosinthea-b-

cframecoordinates, one can use the inverse matrix transformation, as expressed above form.

 $The phase locked loop measures the system frequency and provides the phase synchronous angle \theta (more precisely [sin \theta, cos \theta] for dq transformation block [23]. Very important and necessary feature of grids ideconverter control is the grid synchronization. The synchronization algorithm detects the phase angle of grid voltage to synchronize the phase a$

delivered power. The purpose of this method is to synchronizetheconverteroutputcurrentwiththegrid

voltagetoobtain aunitypowerfactor. Theinputsofthe PLL Page No: 5

model are the three phase voltages measured on the grid sideandthe outputisth etrackedph aseangle.T hePLLmo delis

implemented in synchronous dq reference frame, where aparktransformationisused. The phase-

lockingofthesystemissensedbyadjustingtheq-

axisvoltagetozero.APIcontroller is used for this purpose. The grid angle is obtained by integration of the angular frequency. The grid angle is introduced in the park transform to calculate the dq voltagecomponents.

Thevoltagesourceconverter'scontrolstrategyconsists of abaselevel and a quick inner current control loop that regulates AC currents. DC voltage control is used as the outside controller. Therefore, the DC voltage controller can provide the reference for active current. While the outer loop regulates the load's DC voltage, the inner loop controls power between the DC link and the grid. Figure 5 displays the overall controls cheme.

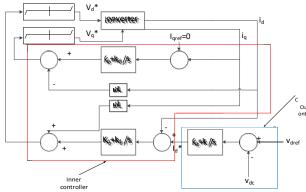


Fig.5Overallcontrolstrategy[17],[28]

The voltage source converter's overall control method is depicted in Figure 5. Current controller (inner current loop) receives the output of Id* from the output DC voltage regulat or block (outside loop). Two PI regulators, one for the

qaxisandtheotherforthedaxis,makeuptheinnercontrollerinthef igure. Active powerflow or DC voltage

level are controlled by active current (id). Reactive powerflow into the grid is managed using reactive current (iq),

asimilarmanner. The difference in inaccuracy between reference current and measured current is fed into the inner controller or current controller.

ThePIregulatorcarrieserror, and feed-

forwardcompensates for decoupling factors. As a result, the desiredconverter voltage is obtained in the dq reference frame. Thefeed-forward is used to mitigate the drawback of cascadecontrol's delayed dynamic response. Because the inner loopvariables' reference values are frequently accessible, they arefed forward for faster and safer operation. To achieve unitypower factor functioning, the controller within the AC/DCconverter manipulates the q axis current. The dq frame isconsideredtoberotatingataconstantspeed,andthedaxisisorien tedalongthegridvoltagevector. Toachieveunitypower factor, thevalue ofigreferenceisset to zero.

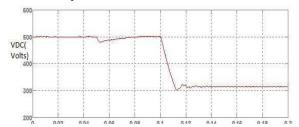


Figure 6 shows dc bus voltage of uncontrolled rectifier. Asloadincreasesthedcbusvoltagedropsconsiderablyinuncontrolled rectifier. Ideally it should remain nearer to 500volts. So before connecting EV batteries to grid this drop involtageshouldbe stabilized.

It is critical to stabilize the uncontrolled converteraction prior to charging vehicle batteries. The load was

keptontheACbus,andafter150milliseconds,whenanadditional load of 200 kW was applied on the DC bus side,the dynamic response of the DC regulator to this rapid loadchange was found to be satisfactory. Within 1.5 cycles, theDC voltage was restored to 500 V, and the power factor ontheACsideremainedclosetounity.Asaresult,thesystem'sstab

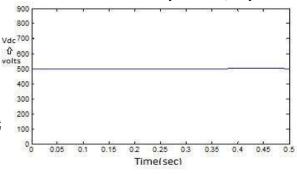


Fig.7StabilisedDCbusvoltage
Thestabilized DCbusvoltageisshownin figure7.

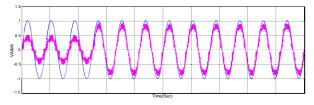


Fig.6DCbusvoltageofuncontrolledcharging

Fig. 8 Strengthen powerfactordueto controlstrategy

The figure 8 above depicts the change of sourcevoltageandsourcecurrentofonephasereadingofcont rolledconverter. Ahealthypowerfactorof 0.997 was establis hed as a result of controlled converter operation. One of the considerations for considering a modified control technique was the current harmonics and the dc bus stability against disturbance.

Fuzzy control has emerged as one of the most fruit fulare as of research in the application of fuzzy set the ory in recentyears[23].LotfiZadeh(1965)developedtheFuzzyLogic tool, which is a mathematical technique for dealingwith uncertainty. It provides a soft computing partnership, which is an important idea in word processing. It provides amethod for dealing with imprecision. The fuzzy theory givesameansofencodinglinguisticconstructslike"many,"" low,""medium,""often,"and"few."Fuzzylogic,ingeneral, provides an inference structure that supports suitable humanreasoning capabilities. Fuzzy logic systems lend themselveswell to approximate reasoning. Fuzzy logic systems respondfaster and more smoothly than conventional systems, andtheir complexity is lower. Fuzzy control in water qualitymanagement, automatic operations automaticcontainercraneoperatingsystems, liftcontrol, nuc learreactor control, car gearbox control, fuzzy memory devices, and fuzzy computers are recent applications in fuzzy systems[23].

In general, the input variables in a fuzzy controlsystem are mapped by sets of membership functions similartothis,referredtoas"fuzzysets."Fuzzificationistheproce ssof transforming a sharp input value to a fuzzy value. Straightlines are used to create the simplest MFs. The simplest

istriangularMF(triMFinfuzzylogictoolbox), which is described by three points forming a triangle. It is easier to apply for controller tuning applications than trapezoidal and other membership functions such as Gaussian and sigmoid. Fuzzyinference systems (FIS) have been used successfully in a wide range of domains, including automatic control, dataclassification, decision analysis, experts yetems, and soon. The technique of mapping a given set of inputs to an output

usingfuzzylogicdescribedbythefuzzy'If-Then'ruledatabase is known as fuzzy inference. Mapping serves as afoundationformakingdecisions. Fuzzyinferenceinvolves all factors such as MFs, fuzzy logic operators, and If-thenprocedures. Therearetwokinds of FISthat can be used. They a re:

1 Mamdani-type

2 Sugeno-type

The way the outputs of these two types of inferencesystemsdiffer. The Mamdani model, established by Ebrahim Mamdani in 1975, is the most often utilised methodology today. The output variable is described using fuzzy sets.

Aprocedureknownasdefuzzificationisemployedtotransformth e fuzzy output to crisp form. Mamdani FIS is suitable forbothMISO(MultipleInputSingleOutput)andMIMO(Multip leInputMultipleOutput).MamdaniFIShastheadvantage of being easier to read, but Sugeno FIS does nothaveanoutputmembershipfunction.Thereisnodefuzzificati on;instead,acrispoutcomeisgeneratedbytakingtheweightedav erageoftherules.SugenoFISisapplicabletoMISOonly.Inhybrid controllerdesignMamdani FIS is selected where ease in Interpretability gainspreferenceoverSugenoFIS.

PI controllers are utilized for inner control, and fuzzy logiccontroliscreatedfortheoutercontrolloop.Fuzzycontrolhas emerged as one of the most important and fruitful fields ofresearchintheapplicationoffuzzysettheoryinrecentyears[24] .Lot if Zadeh (1965) developed the Fuzzy Logictool, which is a mathematical technique for dealing withuncertainty. Fuzzy logic systems lend themselves well toapproximate reasoning. Fuzzy logic systems respond fasterand more smoothly than conventional systems, and controlcomplexity is lower [25]-[27]. Fuzzy control is based onfuzzy logic, which is a logical system that is considerablymore similar to natural human thinking and language thantraditionallogicalsystems[24-

26].Fahidetal.[25]concludedthatwhileproportionalintegrated derivative(PID)controllersarewidelyusedincontrolapplication s,theyperform poorly when applied to nonlinear systems becausecontrollertuningisdifficultduetoalackofknowledgeoft hesystem'sparameters.

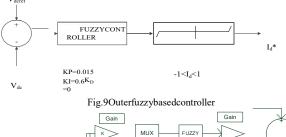
4. HybridControl Algorithm

Asaninput, the inner controller or current controller takes the difference between the reference current and the measured current. The PIr egulator carries the error, and feed-

forwardcompensatesforthedecouplingterms. Asaresult, thedes iredconvertervoltage is obtained in the dqreference frame. The fe ed-forward is used to mitigate the drawback of cascade control's delayed dynamic response. As the reference values. The impact of electrical car penetration on the grid has been observed by replacing the outercontroller with fuzzy logic.

Theinnercontrolleristhesameasinthepriorsituation, and it is base donthevector controller chiqueidea. When compared to the PIcontroller, the fuzzy controller performed better. It eliminated the disadvantage of retuning controllers when the system load changed abruptly and dynamically.

Thefuzzy-basedDCvoltagecontrollerisdepictedinFigure 9. Figure 10 depicts the fuzzy logic controller created inMATLABSimulink.Whenworkingwithafuzzylogiccontroll er, fuzzy rules with fuzzification and defuzzificationshouldbehighlyprecise.



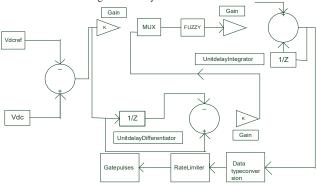


Fig.10OuterfuzzyhybridcontrollerMATLABConfiguration
Fuzzycontrollergaveabetterperformancecompared
to the PID controller. It reduces the drawback
ofretuningcontrollerswhenthesystemloadisabruptlychanging
and dynamic in nature. Fuzzy surface for proposedfuzzy
controller is shown in figure 11 and fuzzy contour inFigure
12.

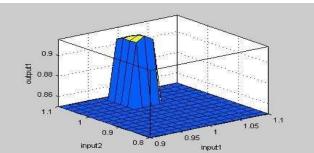


Fig.11Fuzzysurfaceforproposedfuzzycontroller

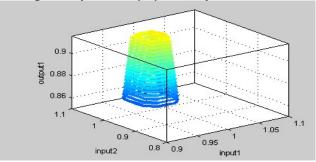


Fig.12 Figurefuzzycontourforhybridcontroller

5. Results

Initially, simulation is performed on an unregulated rectifier. It is discovered that when the load increases, the terminal

voltagelowersandasignificantamountofcurrentharmonicsis discovered. The same increase in load is simulated withhybrid control technique on 6.5Ah and 30Ah batteries, and constantdcbusvoltagewithunitypowerfactoratsourcesideis achieved with significant reduction in harmonics, and theresults obtained with hybrid control technique are compared with PIcontroltechnique. The simulation results are marized here. The results are given for various loading conditions on the distribution grid. The hybrid controltechnique eliminates tuning issues associated with the PIcontroller while also reducing harmonics.

Table2ComparisonofPI & HybridControltechnique

Table2Comparisonori i City brid Controllectinique							
Paramet ers	Uncontroll edrectifier	Controlled Rectifier (with 1Mw load on ACside)					
		6.5 AH		30AH			
		PI	Hybrid	PI	Hybrid		
Vdc(V)	270	490	490	490	490		
Active Power (Watt)	1.14× 10 ⁶	1.6× 10 ⁶	1.1× 10 ⁶	1.6× 10 ⁶	1.1× 10 ⁵		
Reactive power(V ar)	41829	1,58,898	1,10,701	1,56,901	1,04,001		
Voltage harmoni cs	1.48%	0.14%	0.02%	0.14%	0.02%		
Current harmoni cs	43.17%	5.58%	1.96%	3.78%	1.62%		
Power factor		0.9976	0.9952	0.9974	0.9957		

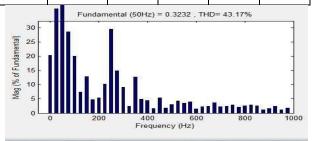


Figure 13 Uncontrolled rectifier with increase in current harmonicsFig.13showsconsiderableamountofcurrentharmonics inthesupplysystemduetouncontrolledrectifier.

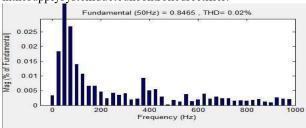


Fig. 14 controlled rectifier voltage harmonics with hybridcontroller

Figure 14 shows that with hybrid control technique voltageharmonics are obtained within the standards.

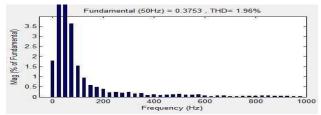


Fig. 15 controlled rectifier current harmonics with hybridcontroller

Figure 15 shows that with proper selection of filter, dc buscapacitor and hybrid control technique harmonics are obtained within the standards

6. Solutionsto EVPenetration

1 Under the correct policies, electric vehicles can aid intheintegrationofrenewableenergysources.

At COP26, the Indian government unveiled its ambitious ambitions for the energy transition, promising to deploy

500GW of renewable electricity generation capacity by 2030 and i ointheworldwideEV30@30campaign.Thecampaignseeks for at least 30% of new vehicle sales to be made up ofelectric vehicles by 2030, while the renewables plan wouldtreble India's renewable energy capacity. These loftygoalsarelinkedtogether. If complemented by a faster decarb onizationofIndia'spowersector,switchingthenation's vehicle from internal combustion toelectricmotorswillreduceemissionsevenmore. Theelectrific ation of transportation will also unleash a vast arrayof distributed energy resources, which, if properly pilotedandmanaged, mayhelpabsorbexcess solar and windpowe r,lowerpricesforconsumersandutilities,andfurtherencourage adoption of EVs.Beyond encouraging EVsales,regulatorysupportforcharginginfrastructureandincen tives for grid-friendly charging are crucial to realizingthis potential. In particular, daytime charging is encouragedto take advantage of the copious solar production during theday.

2 TheenvironmentinIndiaisfavorableforEVs.

Electric vehicle adoption in India increased significantly in2022, with sales of the vehicles tripling to 48 000 from 12000 in 2021. The market share of two-wheelers increased to7%, while the number of new electric three-wheelers sold, at450 000, increased to 55% ahead from 350 000 in China. InTamilNadu,oneofthebiggesttwo-andthree-

wheeler factories is being constructed. The

country'spaceofEVdeploymentvaries, with the biggests aless hare sofEV soccurring in Delhi, Tripura, Assam, and Karnataka, states having pro-EV state policies. For instance, Delhi wants EV sales to account for 25% of all new cars ales by 2024. Polluting vehicles are subject to restrictions, whereas EV sare exempt from road taxes and registration fees.

With financing increased to INR 100 billion (USD 1.2billion), FAME's second phase began in April 2019, withover85%ofthefundinggoingtowardsEVpurchaseincentiv es. Additionally, a component for the deployment ofcharginginfrastructurewasintroducedaspartofthescaleup,ac counting for 10% of the budget. The plan was extended to 2024 in 2021.

InAugust2021,thegovernmentthinktankNITIAayogpub lished Version 1 of its Handbook to Guide EV ChargingInfrastructure in India, drawing even more attention to thisissue. The manual will be updated throughout time with thegoalofassistingauthoritiesintheplanningandimplementatio

IndianMinistryofPoweralsoissuedupdatedrulesandguidelines for infrastructure used for pricing. The number of publicly accessible chargers has increased dramatically overthe past year, going from 900 in 2021 to around 11,000 in 2022.

3 SolarandEVscancomplementoneanother.

ScalingupsolarPVandEVsmightpresentelectricitysystemswit hbothobstaclesandopportunity.LargePVcapacitymightresulti ndaytimeexcessgenerationavailability,whichcancausecurtail ment.Asthesunissetting, the natural propensity for people to recharge

theircarscanconsiderablyincreaseeveningpeakdemands, strain inggridresources and increasing theneed for generating capacity, which may be supplied by fossil fuelgenerators. On the other hand, if EV scan be charged throughout the day using less expensive, cleaner electricity while also assisting in the integration of solar generation, these two technologies can complement one another.

4 TimeofUseTariffs

OneofthekeystrategiesusedtoencourageEVcharginghabitsthat aregoodforthesystemrightnowistimeofusepricing. Timeofuser atesencouragenighttimecharginginIndiatoday, whichlowerspe akdemand. Thegoalwillbetomovechargingtothedaytimewhen solaroutputisgreatestassolargeneration takes upmore andmoreoftheenergy

$\label{eq:mix.5Dynamic} mix. 5 Dynamic charging is more important when it comes to distribution.$

Optimizing the EV charging pattern lowers operational costsby 29% and CO2 emissions by 11%. This indicates real-

timeloadadjustmentthatcouldbeaccomplishedthroughdynami crates. The equivalent operating cost savings between fixedand dynamic daytime charging suggests that the leveladvantagesofshiftingEVdemandintothedaytimemaystill berealized.evenifnon-dynamictechniques do not take into account daily weather variations[21].At the distribution level, where it can control regionalpeaksindemandorrenewableenergysupplies, dynamic charging may offer greater advantages. Dynamic rates canprevent charging demand from exceeding supply, which canhappen with time of use tariffs, for example, during the dayonacloudyday.Locally,thiseffectmightbemorenoticeablet han systemically, where geographical smoothing is applied to both load and renewable energy supply. At the local level, the overlaps between EV and PV are crucial. Colocatingrooftop solar power generating with electriccar chargingoffersthechancetolessentheeffectsofbothtechnologie sonthe local grid. Dynamic charging can be used to help preventgrid congestion in areas where solar power and EV demandare physically further apart, and it could be important to takegrid strengtheningintoaccount.

6 Peak supply can be effectively contributed by EVsThroughvehicle-to-

gridmethods, additional advancements in EV fleet managementa nd assurance of their active involvement in system balance and em issions reduction can be made. Vehicle-to-

gridtechnologyenablescontrolledEVcharginganddischarging and,withthepropertariffstructure,canhelptobalancethepowerg ridandlowerEVowners'chargingcosts.EVswithvehicle-togridfunctionalityhavethepotentialtosignificantlyimprovetheel ectricitysystem.Sinceeachvehicle'sbatterymaybechargedandd ischargedtosmoothoutchangesindemandorsupply,theycaneff ectivelyserveasdistributedstoragewhilealsobeingabletomeetp eakdemandandprovideimprovedancillaryservices.

SmartcharginginIndiaconfrontscomparabledifficulties, but there are even more obstacles to enablingvehicle-to-grid EVs. Complex value chains, the necessity forreliable communication networks and grid-linking protocols, customer acceptability, and the requirement for measures toencourage the provision of ancillary services are a few ofthese.

7 In order for smart charging and the adoption of EVs tooccur, policy support is crucial.

In India, the focus of policy assistance for EVs has so farbeenonreducingcarpurchasingcosts. Until EV prices reacha point where they can be competitive with conventional vehicles, this will continue to be a key area of focus in thenear future. Support for cutting-edge business models, such "energy as a service" methods where battery owners leaserather than buythem, can further speedup adoption.

Future priorities will include further expansions of the infrastructureforcharging. The advantages of day time charging place a strong focus on having charging stations available in places like parking lots or offices where cars arelikelytobe parkedduring the day. workplace Α pricingmanualforcorporationsinDelhiwaspublishedinNovem ber2021bytheDialogueandDevelopmentCommissionofDelhi andtheWorldResourcesInstitute,India,asoneexample of how gaining this is already attention someareas. The combined advantages of improving access to cha rginginfrastructureandenablingdaytimechargingcanbeachiev ed by putting more effort into enabling work chargingstationsacrossIndia.

Itwouldalsobecrucialtohavemorepricingoptionsthatcanencou rage system-friendly charges. The majority of Indianstates offer some time-of-use prices, but they are typicallyonly offered to commercial and industrial users, and givenIndia'scurrentcost-

recoveryframeworks,theydonotencouragedistributioncorpora tionstopursuemoresophisticatedtariffoptions.Inaddition,theo penaccessminimum load requirement has been lowered to permit thedirect delivery of renewable energy to charging stations witha load of greater than 100 kW, and numerous states havealready authorized specific EV charging tariffs across India.A crucial policy step to develop smart charging in India is

toenhancetheregulatoryincentivesfordistributionbusinesses,f orexamplethroughperformance-

basedregulation. Giventhequick growth of EV sales in India, it is necessary to designand put into practice these policy measures so that EVs andtheir capacity become a benefit rather than an additional burden for the country's power industry.

7. Drivers & Further Recommendations for Enhanced EVP enetration on Grid.

- India hasthirteenoftheworld'stoptwentymostpolluted cities. The low-carbon scenario with the'highest' EV penetration is expected to result in a50% reduction in PM 2.5 by 2035 (UNEP, DTU, and IIM-A).
- 2. MostIndiancities'masterplansaimfor60-80percentpublic transport ridership by 2025-2030 (Centre forScienceandEnvironment).
- 3. Large-scaleEVadoptionwillnecessitatebothdemand-sideincentives(e.g.,taxbreaks)andenhancedcharging infrastructure,aswellasintegrated distribution Grid management planning.However, careful planning is required in terms

 $of monitoring and controlling charging in frastruct \\ ure,$

- as an unanticipated increase in EV penetration in aregion can result in an increase in peak load on analready stresseddistribution network.
- Large-scaleEVadoptionwillnecessitatebothdemandsideincentives(e.g.,taxbreaks)andenhancedcharging infrastructure,aswellasintegrateddistributionGridma nagementplanning.
- 5. EVs have the potential to act as distributed storage inthe urban energy system, which could aid in theintegration of intermittent renewables such as windand solar, as well as feed the grid at peak times
 - ifpriceincentivesaredesignedintheformofdynamictar iffsaspartofSmartGridimplementation.
- EVchargingstationsshouldbeconstructedwithrooftop solar generation to reduce reliance on fossilfuels throughout the supply chain and shift towardssustainableenergy.
- 7. Encourage EV manufacturers to create vehicles withswappablebatteries, sothatan EV owner can just go into a charging station, replace his battery with a fully charged battery, and then continue driving. The charging station may charge the batteries during off-peak hours at a lower electricity rate or directly from roof topsolar power.
- 8. Area
 - basedintegratedpublictransportationplanning,EVpro motion,andrenewablegenerationwithdynamic power pricing and Smart Grid tools formonitoring and controlareally ossibilities.
- Theutilitywillauthorizetheconstructionofchargingpoi ntsathousesforEVchargingbasedonthedistributiongr id'savailablecapacityinthatlocation.
- 10. Identification of EV charging sites in an existing distribution network without changing the net work's voltage profile.
- 11. Intelligent charging stations include fast chargers, timers, and the ability to convert to conventional charging mode based on real-time grid conditions/parameters.
- 12. Batterydisposal/recyclingrulespublished bytheMinistryofEnvironment,Forest,andClimateCh ange(Batteries(ManagementandHandling)Rules, 2001) must be carefully observed to preventnegativeenvironmental impactsof batteries.
- 13. Investment in research and development for futurebatterytechnologiesresultsinbatterieswithsubs tantiallyhigherspecificenergy, are more environmenta llyfriendly, and have lower costs. Because batteries account for half of the cost of EVs.
- 14. Localplansforelectricvehicles, subsidies, dedicated parking and related incentives, use of information technology (IT) to find charging stations, partnership with private enterprises, and public car share and lease are other measures that may assist scale up EV incities.

8.CONCLUSION

The paper has pointed out the concerns while charging of Vehicles on Indian distribution grid. It was very necessary topointout the various charging techniques and the distribution grid impacts while EV charging on distribution grid. Vector control technique with hybrid control algorithm can be useful for stability of distribution grid. Concept shown here will be very useful for fast DC charging of electric vehicle batteries. The solutions for massive penetration of EV on Indian property of the paper of the

gridgiveninthepaperwillbeveryusefulforEVpenetrationalong with Recommendation's and suggestions given in thepaper.

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